

2.4 (1)

$$y''(t) + 4y'(t) + 3y(t) = f(t), \quad y(0) = y'(0) = 1, \quad f(t) = \varepsilon(t)$$

零输入:

$$\therefore \text{微分方程求解可得: } \lambda^2 + 4\lambda + 3 = 0 \quad \therefore \lambda_1 = -3 \quad \lambda_2 = -1$$

$$\therefore y_{zi}(t) = C_{2i1} e^{-3t} + C_{2i2} e^{-t}$$

$$\therefore y(0) = y_{zi}(0) + y_{zs}(0)$$

$$\therefore y'(0) = y'_{zi}(0) + y'_{zs}(0)$$

$$\therefore y_{zi}(0) = 1, \quad y'_{zi}(0) = 1 \quad \therefore C_{2i1} = -3 \quad C_{2i2} = -1$$

$$\therefore y_{zi}(t) = (-e^{-3t} + 2e^{-t}) \varepsilon(t)$$

$$\text{零状态: } y''_{zs}(t) + 4y'_{zs}(t) + 3y_{zs}(t) = \varepsilon(t)$$

$$\therefore y_{zs}(0) = y'_{zs}(0) = 0$$

$$\therefore \int_{0-}^{0+} y''_{zs}(t) dt + 4 \int_{0-}^{0+} y'_{zs}(t) dt + 3 \int_{0-}^{0+} y_{zs}(t) dt = \int_{0-}^{0+} \varepsilon(t) dt$$

$$\therefore y'_{zs}(0+) - y'_{zs}(0-) + 4[y_{zs}(0+) - y_{zs}(0-)] = 0$$

$$\therefore y'_{zs}(0+) - y'_{zs}(0-) = 0 \quad \therefore y'_{zs}(0+) = y'_{zs}(0-) = 0$$

$$t > 0 \text{ 时 } y''_{zs}(t) + 4y'_{zs}(t) + 3y_{zs}(t) = 1$$

$$\therefore y_{zs}(t) = C_{2s1} e^{-t} + C_{2s2} e^{-3t} + P_0 \quad \therefore P = \frac{1}{3}$$

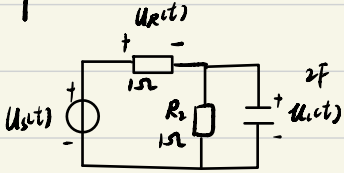
$$\therefore y'_{zs}(t) = -C_{2s1} e^{-t} - 3C_{2s2} e^{-3t}$$

$$\therefore \text{代入得 } C_{2s1} = -\frac{1}{2} \quad C_{2s2} = \frac{1}{6}$$

$$\therefore y_{zs}(t) = \left(-\frac{1}{2}e^{-t} + \frac{1}{6}e^{-3t} + \frac{1}{3}\right) \varepsilon(t)$$

$$\therefore y(t) = \left(-\frac{5}{6}e^{-3t} + \frac{3}{2}e^{-t} + \frac{1}{3}\right) \varepsilon(t)$$

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$$\therefore f(t) = u_s(t) \quad y(t) = u_c(t)$$

$$\begin{cases} u_R(t) + u_c(t) = u_s(t) \\ u_c(t) + C u_c'(t) = u_R(t) \end{cases}$$

$$\therefore \text{消去得 } 2u_c(t) + 2u_c'(t) = u_s(t)$$

$$\therefore \text{微分方程为 } 2u_c(t) + 2\frac{du_c(t)}{dt} = u_s(t)$$

冲激响应:

∴ 微分方程解得

$$\left. \begin{aligned} 2u_c(t) + 2u_c'(t) &= \delta(t) \\ u_c'(0^-) = u_c(0^-) &= 0 \end{aligned} \right\} \begin{aligned} \lambda &= -1 \\ \therefore &= C_1 e^{-t} \end{aligned}$$

$$\int_0^{0+} u_c(t) dt + \int_0^{0+} u_c'(t) dt = \frac{1}{2}$$

$$u_c'(t) = a\delta(t) + f_0(t) \quad a \int_0^{0+} \delta(t) dt = u_c(0+) - u_c(0^-) = a$$

$$\therefore a = \frac{1}{2}$$

$$\checkmark \therefore u_c(0+) - u_c(0^-) = a \quad \therefore u_c(0+) = a + u_c(0^-) = \frac{1}{2}$$

$t > 0$  时

$$\therefore h_c(t) = C e^{-t} \quad \text{代入得 } C = 0.5$$

$$\therefore h_c(t) = 0.5 e^{-t} \varepsilon(t)$$

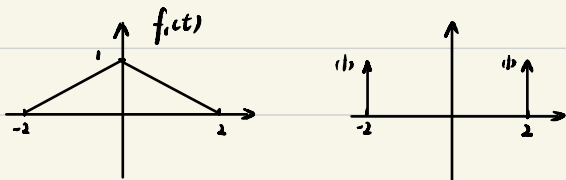
$$\text{阶跃响应 } g_c(t) = \int_{-\infty}^t h_c(t) dt = 0.5 (e^{-t} - 1) \varepsilon(t)$$

∴ 冲激响应  $h(t) = 0.5e^{-t} \varepsilon(t)$

阶跃响应  $g(t) = 0.5(1 - e^{-t}) \varepsilon(t)$

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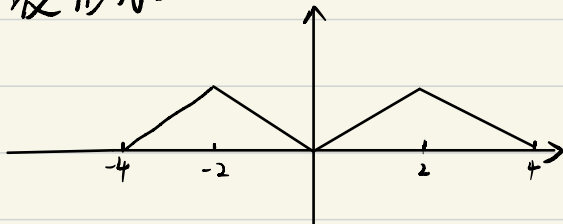
(1)  $f_1(t) * f_2(t)$



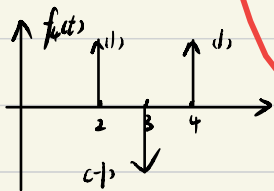
$$f(t) = f_1(t) * f_2(t) = f_1(t) * (\delta(t+2) + \delta(t-2))$$

$$= f(t+2) + f(t-2)$$

∴ 波形为:

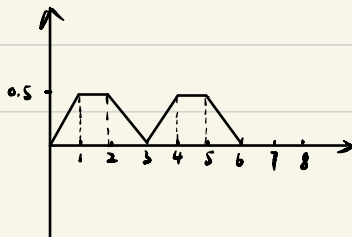


(3)  $f_1(t) * f_4(t)$



$$f_1(t) * f_4(t) = f_1(t) * (\delta(t-2) - \delta(t-3) + \delta(t-4))$$

$$= f(t-2) - f(t-3) + f(t-4)$$



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$$(1) f_1(t) = \delta(t) - \delta(t-4) \quad f_2 = \sin(\pi t) \delta(t)$$

$$\begin{aligned} \therefore f(t) &= f_2^{(1)} * f_1^{(1)} = (\delta(t) - \delta(t-4)) * \int_{-\infty}^t \sin(\pi \tau) \delta(\tau) d\tau \\ &= (\delta(t) - \delta(t-4)) * \left[ \frac{1}{\pi} (1 - \cos \pi t) \right] \delta(t) \\ &= \frac{1}{\pi} (1 - \cos(\pi t)) \delta(t) - \frac{1}{\pi} (1 - \cos(\pi(t-4))) \delta(t-4) \\ &= \frac{1}{\pi} (1 - \cos(\pi t)) \delta(t) - \frac{1}{\pi} (1 - \cos(\pi t)) \delta(t-4) \\ &= \frac{1}{\pi} (1 - \cos(\pi t)) [\delta(t) - \delta(t-4)] \end{aligned}$$

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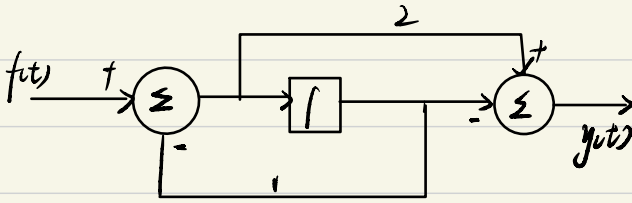
$$\begin{aligned} f(t) &= h(t) * \delta(t) = h^{(1)}(t) * \delta^{(1)}(t) \\ &= (\delta(t) - \delta(t-2)) * \delta(t) \\ &= \delta(t) * \delta(t) - \delta(t-2) * \delta(t) \\ &= t \delta(t) - \delta(t-2) * (t \delta(t)) \\ &= t \delta(t) - (t-2) \delta(t-2) \end{aligned}$$

$$(2) f_1(t) = \delta(t-2) - \delta(t-3)$$

$$\begin{aligned} f(t) &= h(t) * f_1(t) = [\delta(t) - \delta(t-2)] * [\delta(t-2) - \delta(t-3)] \\ &= [\delta(t) - \delta(t-2)] * [(t-2) \delta(t-2) - (t-3) \delta(t-3)] \end{aligned}$$

$$= (t-2) \delta(t-2) - (t-3) \delta(t-3) - (t-4) \delta(t-4) + (t-5) \delta(t-5)$$

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$$f(t) - x(t) = x'(t) \quad \therefore f(t) = x'(t) + x(t)$$

$$2x'(t) - x(t) = y(t) \quad y(t) = 2x'(t) - x(t)$$

$$y'(t) = 2x''(t) - x'(t) \quad \therefore y'(t) + y(t) = 2(x'(t) + x(t))' - (x'(t) + x(t))$$

$$= 2f'(x) - f(x)$$

$$\therefore y'(t) + y(t) = 2f'(x) - f(x)$$

$$\therefore h'(t) + h(t) = 2\delta'(x) - \delta(x)$$

$$\therefore h'(0-) = h(0-) = 0$$

$$\text{又} \because \lambda + 1 = 0 \quad \lambda = -1 \quad \therefore h(t) = (C_1 e^{-t}) \delta(t)$$

$$\text{设 } h'(t) = a\delta'(x) + b\delta(x) + f_0(t)$$

$$\therefore h(t) = \int_0^{0+} a\delta'(x) + b\delta(x) + f_0(t) dt$$

$$= a\delta(x) + f_1(t)$$

$$\therefore h'(t) + h(t) = a\delta'(x) + (a+b)\delta(x) + f_0(t) + f_1(t)$$

$$\therefore a=2 \quad b=-3$$

$$\therefore \int_{0^-}^{0^+} h'(t) dt = \int_{0^-}^{0^+} 2\delta'(x) - 3\delta(x) + f_0(t) dt = -3$$

$$\therefore h(0_+) - h(0_-) = -3 \quad \therefore h(0_+) = -3$$

$$\therefore h(t) = (C_1 e^{-t}) \varepsilon(t) \quad \therefore \text{代入得 } C_1 = -3$$

$$\therefore h(t) = (-3e^{-t}) \varepsilon(t) + 2\delta(t)$$

2.30

$$y(t) = f(t) * h_1(t) + f(t) * h_2(t) * h_1(t) * h_3(t)$$

$$= f(t) * (h_1(t) + h_2(t) * h_1(t) * h_3(t))$$

$$h_2(t) * h_1(t) * h_3(t) = \delta(t-1) * \varepsilon(t) * -\delta(t) = -\varepsilon(t-1)$$

$$h_1(t) = \varepsilon(t)$$

$$\therefore y(t) = f(t) * (\varepsilon(t) - \varepsilon(t-1))$$

$$\text{当 } f(t) = \delta(t) \text{ 时 } \quad h(t) = \varepsilon(t) - \varepsilon(t-1)$$

