

故系统响应的冲激响应为 $f_1(t) = g(t) = \frac{1}{2}e^{-t}\varepsilon(t)$

2.16

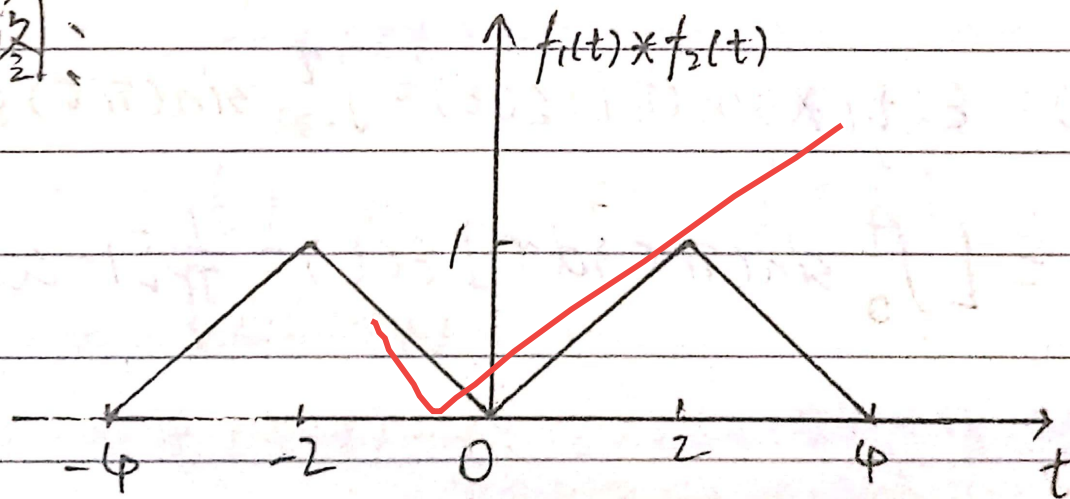
(1) $f_2(t) = \delta(t+2) + \delta(t-2)$

解: 根据卷积的性质

$$\begin{aligned} f_1(t) * f_2(t) &= f_1(t) * \delta(t+2) + f_1(t) * \delta(t-2) \\ &= f_1(t+2) * f_1(t-2) \end{aligned}$$

$\Sigma U_c'(t) =$

波形如图:



= 0

本

源本

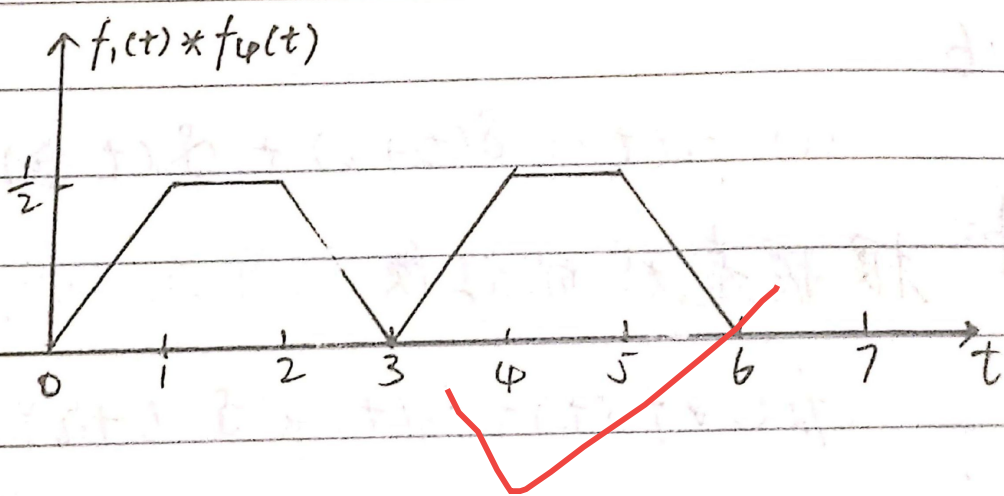
$$(3) f_4(t) = \delta(t) - \delta(t-2) + \delta(t-3) - \delta(t-4)$$

根据卷积的性质,

$$f_1(t) * f_4(t) = f_1(t) * \delta(t) - f_1(t) * \delta(t-2) + f_1(t) * \delta(t-3) - f_1(t) * \delta(t-4)$$

$$= f_1(t) - f_1(t-2) + f_1(t-3) - f_1(t-4)$$

波形如图:



2.17 (7) 设 $f(t) = \varepsilon(t) * \sin(\pi t) \varepsilon(t)$, 则

解: $f(t) = \varepsilon(t) * \sin(\pi t) \varepsilon(t) = \int_{-\infty}^t \sin(\pi \tau) \varepsilon(\tau) d\tau$
 $= \left[\int_0^t \sin(\pi \tau) d\tau \right] \varepsilon(t) = \frac{1}{\pi} [1 - \cos(\pi t)] \varepsilon(t)$

$$\begin{aligned}
 f_1(t) * f_2(t) &= [\varepsilon(t) - \varepsilon(t-\varphi)] * \sin(\pi t) \varepsilon(t) \\
 &= \varepsilon(t) * \sin(\pi t) \varepsilon(t) - \varepsilon(t-\varphi) * \sin(\pi t) \varepsilon(t) \\
 &= f(t) - f(t-\varphi)
 \end{aligned}$$

故 $f_1(t) * f_2(t) = f(t) - f(t-\varphi)$

$$= \frac{1}{\pi} [1 - \cos(\pi t)] \varepsilon(t) - \frac{1}{\pi} [1 - \cos \pi(t-\varphi)] \varepsilon(t-\varphi)$$

$$= \frac{1}{\pi} [1 - \cos(\pi t)] [\varepsilon(t) - \varepsilon(t-\varphi)]$$

2.18 由各波形图可得 $h(t) = \varepsilon(t) - \varepsilon(t-2)$

解: $f_1(t) = \varepsilon(t-2) - \varepsilon(t-3)$

$$f_2(t) = \frac{1}{2} t [\varepsilon(t) - \varepsilon(t-2)]$$

$$= \frac{1}{2} t \varepsilon(t) - \frac{1}{2} (t-2) \varepsilon(t-2) - \varepsilon(t-2)$$

$$f_3(t) = \frac{1}{2} t [\varepsilon(t) - \varepsilon(t-2)] + (2 - \frac{1}{2} t) [\varepsilon(t-2) - \varepsilon(t-4)]$$

$$= \frac{1}{2} t \varepsilon(t) - (t-2) \varepsilon(t-2) + \frac{1}{2} (t-4) \varepsilon(t-4)$$

源本

(1) 当输入为单位阶跃函数时, 系统零状态响应

为:

$$y_{zs1}(t) = h(t) * \varepsilon(t) = [\varepsilon(t) - \varepsilon(t-2)] * \varepsilon(t)$$
$$= t\varepsilon(t) - (t-2)\varepsilon(t-2)$$

(2) 当输入为 $f(t)$ 时, 系统为零状态响应为:

$$y_{zs2}(t) = h(t) * f(t) = [\varepsilon(t) - \varepsilon(t-2)] * [\varepsilon(t-2) - \varepsilon(t-4)]$$

$$= y_{zs1}(t-2) - y_{zs1}(t-4)$$

$$= (t-2)\varepsilon(t-2) - (t-3)\varepsilon(t-3) - (t-4)\varepsilon(t-4) + (t-5)\varepsilon(t-5)$$

2.26 由左边加法器可得: $x'(t) = f(t) - x(t)$

解: 即 $x'(t) + x(t) = f(t)$

由右边加法器得, $y(t) = 2x'(t) - x(t)$

等式两边取微分得: $y'(t) = 2x''(t) - x'(t)$

两式相加得 $y'(t) + y(t) = 2x''(t) + 2x'(t) - [x'(t) - x(t)]$

$$= 2f'(t) - f(t)$$

设 $h_1(t)$ 满足 $h_1'(t) + h_1(t) = \delta(t)$, $h_1(0+) = 1$

则有: $h_1(t) = e^{-t} \varepsilon(t)$

故系统的冲激响应为: $h(t) = 2h_1'(t) - h_1(t)$
 $= 2\delta(t) - 3e^{-t} \varepsilon(t)$

2.30 令 $f(t) = \delta(t)$, 则加法器两个输入分别为

解: $h_{11}(t) = y_1(t) = f(t) * h_1(t) = \delta(t) * \varepsilon(t) = \varepsilon(t)$

$h_{12}(t) = y_2(t) = f(t) * h_2(t) * h_1(t) * h_3(t)$

$$= \delta(t) * \delta(t-1) * \varepsilon(t) * [-\delta(t)] = \varepsilon(t) - \varepsilon(t-1)$$

故复合系统的冲激响应为: $h(t) = h_{11}(t) + h_{12}(t)$

$$= \varepsilon(t) - \varepsilon(t-1)$$